3-4 person groups preferred

Projects

Home work Sendez. CNN lactore Honday

Deliverables: Poster & Report & main code (plus proposal, midterm slide)

Topics your own or chose form suggested topics. Some **physics/engineering inspired**.

April 26 groups due to TA (if you don't have a group, ask in piazza we can help). TAs will construct groups after that.

May 5 proposal due. TAs and Peter can approve.

Proposal: One page: Title, a large paragraph, data, weblinks, references.

May 20 Midterm slide presentation. Presented to a subgroup of class.

June 5 final poster. Uploaded June 3

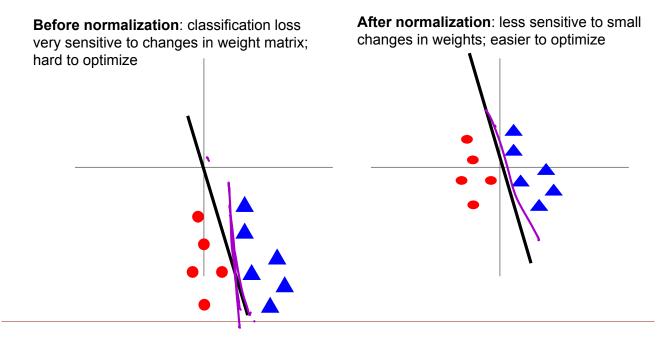
Report and code due Saturday 15 June.

Q: Can the final project be shared with another class?

If the other class allows it it should be fine. You cannot turn in an identical project for both classes, but you can share common infrastructure/code base/datasets across the two classes.

No cut and paste from other sources without making clear that this part is a copy. This applies to other reports or things from internet. Citations are important.

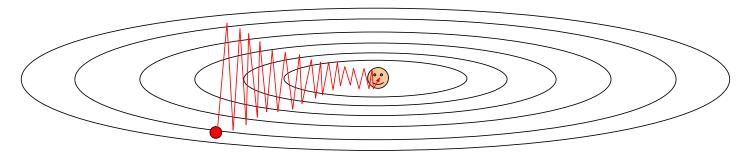
Last time: Data Preprocessing



Optimization: Problems with SGD

What if loss changes quickly in one direction and slowly in another? What does gradient descent do?

Very slow progress along shallow dimension, jitter along steep direction



Loss function has high **condition number**: ratio of largest to smallest singular value of the Hessian matrix is large



Optimization: Problems with SGD

What if the loss function has a **local minima** or **saddle point**?

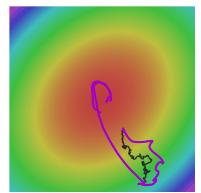
Zero gradient, gradient descent gets stuck

> Saddle points much more common in high dimension

Optimization: Problems with SGD

Our gradients come from minibatches so they can be noisy!

$$L(W) = \frac{1}{N} \sum_{i=1}^{N} L_i(x_i, y_i, W)$$
$$\nabla_W L(W) = \frac{1}{N} \sum_{i=1}^{N} \nabla_W L_i(x_i, y_i, W)$$



SGD + Momentum

SGD

$$x_{t+1} = x_t - \alpha \nabla f(x_t)$$

while True:

dx = compute_gradient(x)

x += learning_rate * dx

SGD+Momentum

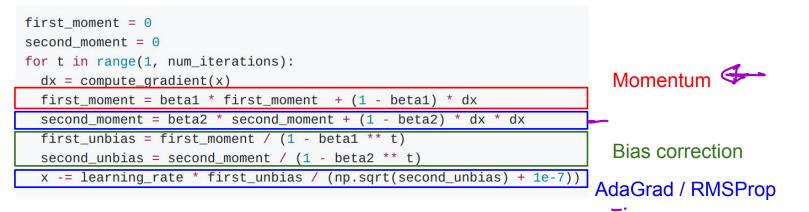
$$v_{t+1} = \rho v_t + \nabla f(x_t)$$

$$x_{t+1} = x_t - \alpha v_{t+1}$$

vx = 0
while True:
 dx = compute_gradient(x)
 vx = rho * vx + dx
 x += learning_rate * vx

- Build up "velocity" as a running mean of gradients
- Rho gives "friction"; typically rho=0.9 or 0.99

Adam (full form)

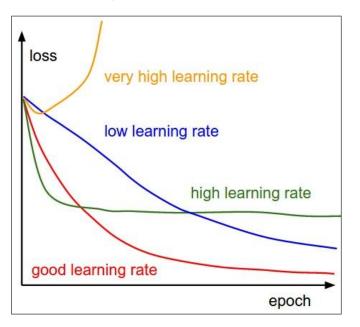


Bias correction for the fact that first and second moment estimates start at zero

Adam with beta 1 = 0.9,

beta2 = 0.999, and learning_rate = 1e-3 or 5e-4 is a great starting point for many models!

SGD, SGD+Momentum, Adagrad, RMSProp, Adam all have **learning rate** as a hyperparameter.



=> Learning rate decay over time!

step decay:

e.g. decay learning rate by half every few epochs.

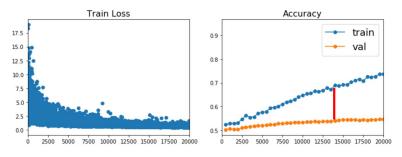
exponential decay:

$$lpha=lpha_0 e^{-kt}$$

1/t decay:

$$lpha=lpha_0/(1+kt)$$

How to improve single-model performance?



Regularization

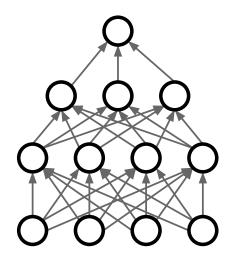
Regularization: Add term to loss

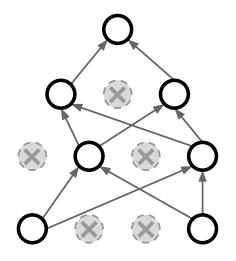
$$L = rac{1}{N} \sum_{i=1}^{N} \sum_{j
eq y_i} \max(0, f(x_i; W)_j - f(x_i; W)_{y_i} + 1) + \lambda R(W)$$

In common use:L2 regularization $R(W) = \sum_k \sum_l W_{k,l}^2$ (Weight decay)L1 regularization $R(W) = \sum_k \sum_l |W_{k,l}|$ Elastic net (L1 + L2) $R(W) = \sum_k \sum_l \beta W_{k,l}^2 + |W_{k,l}|$

Regularization: Dropout

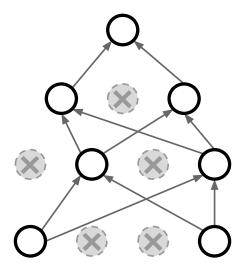
In each forward pass, randomly set some neurons to zero Probability of dropping is a hyperparameter; 0.5 is common





Homework

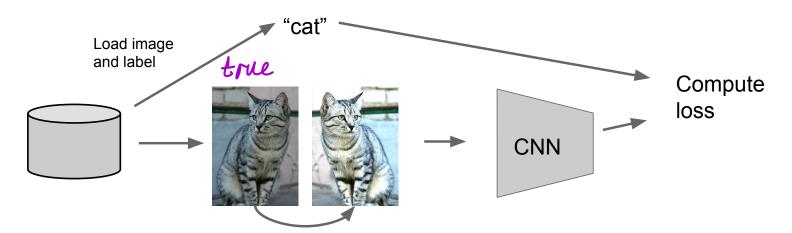
Regularization: Dropout How can this possibly be a good idea?



Forces the network to have a redundant representation; Prevents co-adaptation of features



Regularization: Data Augmentation



Data Augmentation Get creative for your problem!

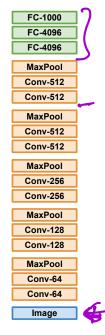
Random mix/combinations of :

- translation
- rotation
- stretching
- shearing,
- lens distortions, ... (go crazy)

+simulated data using physical model.

Transfer Learning with CNNs

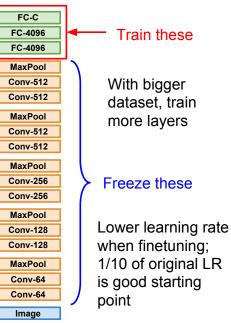
1. Train on Imagenet



2. Small Dataset (C classes) FC-C FC-4096 Reinitialize FC-4096 this and train MaxPool Conv-512 Conv-512 MaxPool Conv-512 Conv-512 Freeze these MaxPool Conv-256 Conv-256 MaxPool Conv-128 Conv-128 MaxPool Conv-64 Conv-64 Image

Donahue et al, "DeCAF: A Deep Convolutional Activation Feature for Generic Visual Recognition", ICML 2014 Razavian et al, "CNN Features Off-the-Shelf: An Astounding Baseline for Recognition", CVPR Workshops 2014

3. Bigger dataset



Predicting Weather with Machine Learning: Intro to ARMA and Random Forest

Emma Ozanich

PhD Candidate, Scripps Institution of Oceanography

Background

- Shi et al NIPS 2015
 - Predicting rain at different time lags
 - Shows convolutional lstm vs nowcast models vs fullyconnected lstm
 - Used radar echo (image) inputs
 - Hong Kong, 2011-2013,
 - 240 frames/day
 - Selected top 97 rainy days
 - ≁ Note: <10% of data used!</p>
 - Preprocessing: k-means clustering to denoise
 - ConvLSTM has better performance and lower false alarm (lower left)

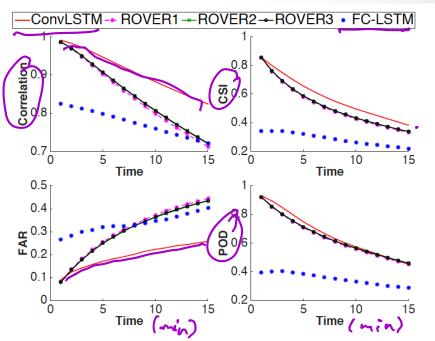


Figure 1: (Larger Version) Comparison of different models based on four precipitation nowcasting metrics over time.

CSI: hits/(hits+misses+false) FAR: false/(hits+false) POD: hits/(hits+misses) false = false alarm

Background

> McGovern et al 2017 BAM -

• Decision trees used in meteorology since mid-1960s

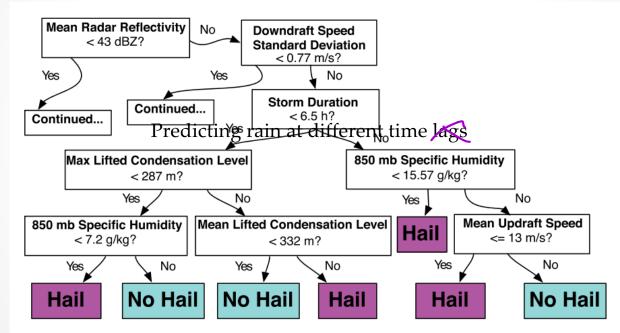
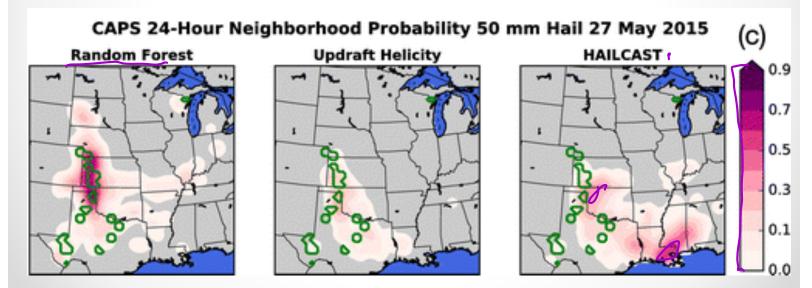


Fig. 1. An example of a decision tree for predicting if hail will occur. A version of this decision tree first appeared in Gagne (2016).

Background

McGovern et al 2017 BAM -

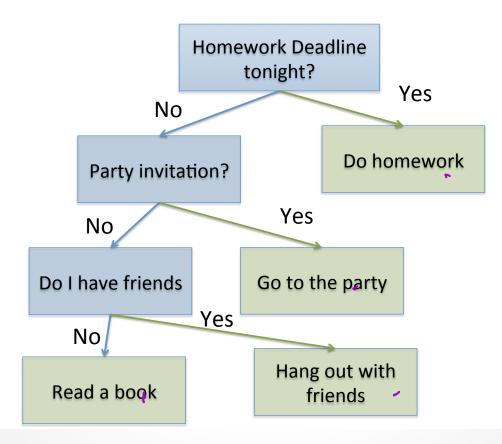
- Green contours = hail occurred (truth)
- Physics based method: Convection-allowing model (CAM)
 - o Doesn't directly predict hail
- Random forest predicts hail size (Γ) distribution based on weather
- HAILCAST = diagnostic measure based on CAMs
- Updraft Helicity = surrogate variable from CAM



McGovern et al 2017, Bull. Amer. Meteor. Soc. 98:10, p. 2073-2090.

Decision Trees

Algorithm made up of conditional control statements



Decision Trees

McGovern et al 2017 BAM -

Decision trees used in meteorology since mid-1960s

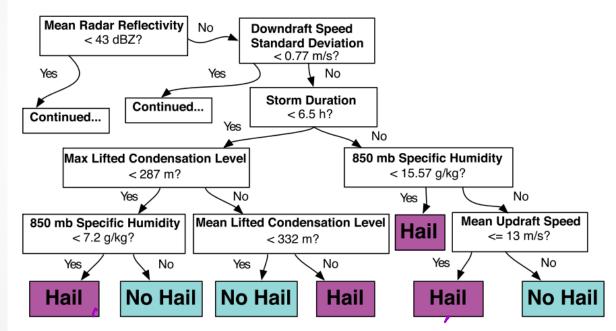
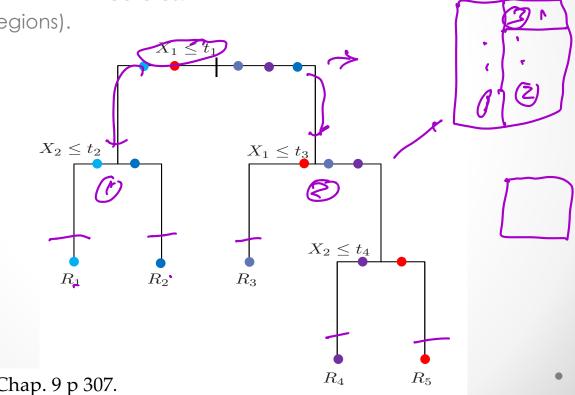


Fig. 1. An example of a decision tree for predicting if hail will occur. A version of this decision tree first appeared in Gagne (2016).

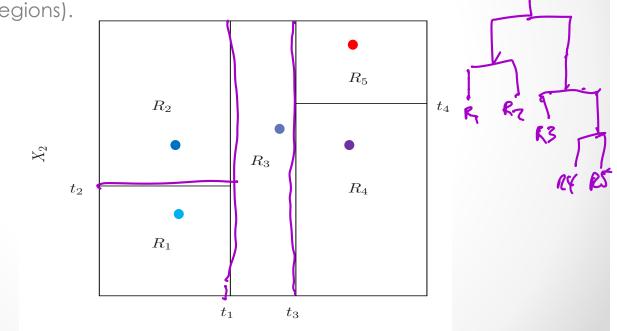
- Divide data into distinct, non-overlapping regions R1,..., RJ
- Below $y_i = \text{color} = \text{continuous target}$ (<blue = 1 and >red = 0).
- x_i , i = 1,...,5 samples
- $x_i = [X_1, X_2]$, with P = 2 features.
- j = 1,...,5 (5 regions).



Hastie et al 2017, Chap. 9 p 307.

Tree-building

- Or, consecutively partition a region into non-overlapping rectangles
- $y_i = \text{color} = \text{continuous target}$ (<blue = 1 and >red = 0).
- x_i , i = 1,...,5 samples
- $x_i = [X_1, X_2]$, with P = 2 features.
- j = 1,..,5 (5 regions).



Hastie et al 2017, Chap. 9 p 307.

 X_2

- How to optimize a regression tree?
- Randomly select t_1

 $R_1(j, \mathbf{t}_1) = \{ X | X_j \leq \mathbf{t}_1 \}$

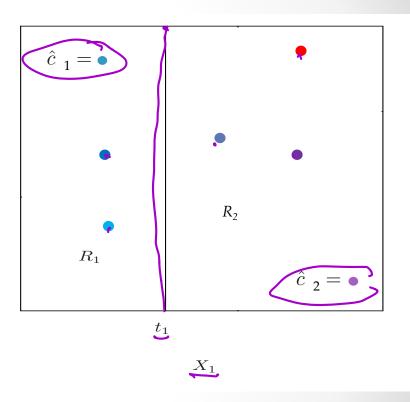
 $R_2(j, \ensuremath{ \mathbf{t}}_1) \mbox{=} \{X | X_j > \ensuremath{ \mathbf{t}}_1\}$, $j \mbox{=} 1$

• Assign region labels:

$$\hat{c}_m = \operatorname{ave}(y_i | x_i \in R_m).$$

o Example-

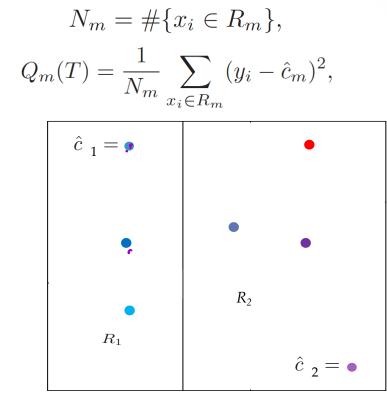
 $\hat{c}_1 = \bullet$ $\hat{c}_2 = \bullet$



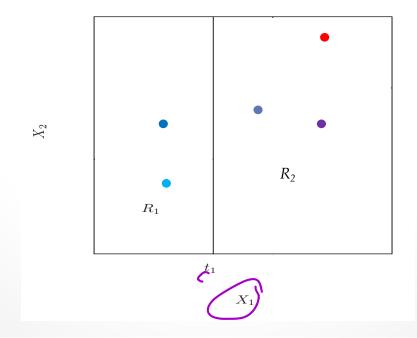
• Compute the cost of the tree, $Q_m(T)$,

 X_2

• Minimize $Q_m(T)$ by changing t_1



- Algorithm to build tree T_b
- In our simple case, m = 1 and p = 2
- Daughter nodes are equivalent to regions
 - 1. Select m variables at random from the p variables.
 - 2. Pick the best variable/split-point among the m.
 - 3. Split the node into two daughter nodes. 1



mcp

Bootstrap samples

- Select a subset of the total samples, (x_i^*, y_i^*) , i = 1, ..., N
- Draw samples uniformly at random with replacement
- Example: If I = 5 originally, we could choose N = 2
- Samples are drawn assuming equal probability:

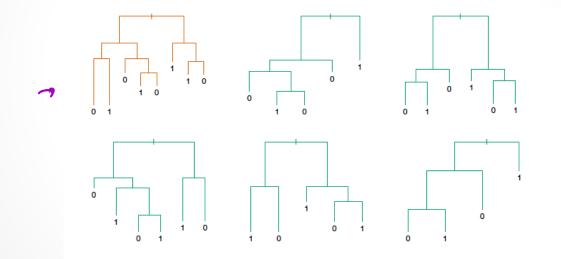
• If x_i , y_i is drawn more often, it is more likely

$$P_{\hat{\mathcal{F}}}\big\{(X,Y) = (x,y)\big\} = \begin{cases} \frac{1}{n}, & \text{if } (x,y) = (x_i,y_i) \text{ for some } i\\ 0 & \text{otherwise} \end{cases}$$

 \circ (X,Y) are the expectations of the underlying distributions

Random Forest

- Example of binary classification tree from Hastie et al 2017
- Orange: trained on all data
- Green: trained from different bootstrap samples
- Then, average the (green) trees



Random Forest

- Bootstrap + bagging => more robust RF on future test data
- Train each tree T_b on bootstrap sampling

Algorithm 15.1 Random Forest for Regression or Classification.

- 1. For b = 1 to B:
 - (a) Draw a bootstrap sample \mathbf{Z}^* of size N from the training data.
 - (b) Grow a random-forest tree T_b to the bootstrapped data, by recursively repeating the following steps for each terminal node of the tree, until the minimum node size n_{min} is reached.
 - i. Select m variables at random from the p variables. ii. Pick the best variable/split-point among the m. iii. Split the node into two daughter nodes.
- 2. Output the ensemble of trees $\{T_b\}_{1}^{B}$.

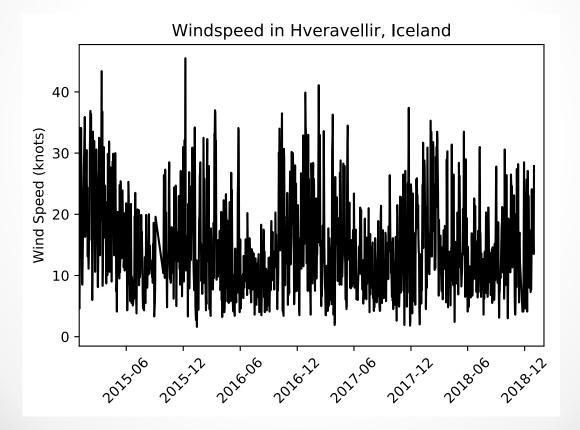
To make a prediction at a new point x:

Regression:
$$\hat{f}_{rf}^B(x) = \frac{1}{B} \sum_{b=1}^B T_b(x)$$
.

Hastie et al 2017, Chap. 15 p. 588

Timeseries (TS)

• Timeseries: one or more variables sampled in the same location at successive time steps



ARMA

- Autoregressive moving-average :
 - o (weakly) stationary stochastic process
 - o Polynomials model process and errors as polynomial of prior values

Autogressive (order p)

- Linear model of past (lagged) and future values
- o plags



- ο φ_i are (weights) parameters
- o c is constant
- \circ ϵ_t is white noise (WGN)
- Note, for stationary processes, $|\phi_i| < 1$.
- Moving-average (order q)
 - Linear model of past errors
 - o q lags
 - Below, assume $<X_t>=0$ (expectation is 0)

$$X_{t} = c + \sum_{i=1}^{q} \theta_{i} \varepsilon_{t-i} + \varepsilon_{t}$$

ARMA

- Autoregressive moving-average :
 - o (weakly) stationary stochastic process
 - Linear model of prior values = expected value term + error term + WGN
- ARMA: AR(p) + MA(q)

 $X_{t} = c + \sum_{i=1}^{p} \varphi_{i} X_{t-i} + \sum_{i=1}^{q} \theta_{i} \varepsilon_{t-i} + \varepsilon_{t}$

Data retrieval

Just a few public data sources for physical sciences...

- NOAA:
 - Reanalysis/model data, research cruises, station observations, gridded data products, atmospheric & ocean indices timeseries, heat budgets, satellite imagery
- NASA:
 - EOSDIS, gridded data products (atmospheric), satellite imagery, reanalysis/model data, meteorological stations, DAAC's in US
- IMOS:
 - o ocean observing hosted by Australian Ocean Data Network
- USGS Earthquake Archives
- CPC/NCEI:
 - o gridded and raw meteorological and oceanographic
- ECMWF
 - o global-scale weather forecasts and assimilated data

•••

Possible data formats:

- o CSV
- o NetCDF
- HDF5/HDF-EOS
- o Binary
- JPEG/PNG
- ASCII text

Basic data cleaning

- "[ML for physical sciences] is 80% cleaning and 20% models" ~ paraphrased, Dr. Gerstoft
- Basic cleaning for NOAA GSOD to HW necessary
 - Remove unwanted variables (big data is slow) /
 - Replaced "9999" filler values with NaN
 - Converted strings to floats (i.e. for wind speed) -
 - Created a DateTime index
- Physical data needs cleaning, reorganizing
- Quality-controlled data still causes bugs
- Application-specific

Data for HW

-> BigQuery:

- Open-source database hosted by Google
- Must have Google account
- o 1 TB data free/ month

	I.google.com/bigquery?filter=solution-type:di				oogle.com/bigquery?filter=solution-type: Sol 🎓 Download and Set 🛚 🕊 Course	-0 -0	🗆 🥞 ar Bookm
Googl C	Q Search for solutions		≡ Googl	÷	Q Search for solutions		
BigQu Marketplace			SANDBOX	Marketplace > Datasets			
Filter by queries	125 results		Saved queries	Filter by	21 results		
tory TYPE Datasets Called que CATEGORY CATEGORY Analytics (6)	Argentina Real Estate Listings Properati Monthly property listing data for Argentina since 2016	City of Austin City of Austin City of Austin City of Austin crime data for 2014 and 2015	Job history Transfers Scheduled que BI Engine Resources Q. Search fery	TYPE Datasets ③ CATEGORY Climate ③	Cloud-to-Ground Lightning Strikes NOA Aggregated lightning strike data from 1987 to 2018	GHCN Daily NOAA Global Historical Climatology Network Daily Weather Data	
dept-temp iggenery-pu iggener	Bitcoin Cash Cryptocurrency Dataset Google Cloud Public Datasets Pro The Bitcoin Cash blockchain loaded to BigQuery and updated daily	Bitcoin Cash On-Chain Transaction Data (Sample) cmorq Easy access to on-chain transaction data	adapt-conf		GHCN Monthly NGAA Global Historical Climatology Network Monthly Weather Data	Global Historical Tsunami Database NOA Tsunami and source event data as far back as 2000 BC	
Maps (1) Public safety (13) Science & research (42) Social (3) Transportation (1) Other (11)	B Bitcoin Gold On-Chain Transaction Data (Sample) cmorq Easy access to on-chain transaction data	Bitcoin On-Chain Transaction Data (Sample) cmorq Easy access to on-chain transaction data			Clobal Hurricane Tracks (IBTrACS) NOAA Tropical Cyclone/Hurricane position and intensity	COES-16 NOAA Geostationary Operational Environmental Satellite data	,
	BITCOMEY Bitcoin SV On-Chain Transaction Data (Sample) emorg	P Brazil Real Estate Listings Properati Monthly property listing data for Brazil kines 2016			COES-17 NOAA Geostationary Operational	SSOD NOAA Global Surface Summary of the Day	r

NOAA GSOD dataset

Data for HW

- How to get BigQuery data?
- bigquery package in Jupyter Notebook (SQL server)

💭 jupyter BigC	Uery Tutorial Last Checkpoint: 04/05/2019 (autosaved)	Page 1	Control Panel						
File Edit View	dit View Insert Cell Kernel Widgets Help								
B + × 4 B	↑ ↓ N Run ■ C → Code ↓ Walidate		emory: CPU: PU:						
clien impor	<pre>in [1]: from google.cloud import bigquery client = bigquery.Client() import time import numpy as np</pre>								
Yearly datasets years = \$2008,2009,2010,2011,2012,2013,2014,2015,2016,2017,2018 for y in years: sql = {?" SELECT *									
F	Casets SELECT * FROM `bigguery-public-data.noaa_gsod.gsod{0}` Simple SQL query 'f.format(y)								
Pickle	<pre>0=time.time() f = client.guery(sql).to_dataframe() rint(time.time()-t0) f.to_pickle('noaa_gsod.gsod' + str(y)) rint(time.time()-t0) DF</pre>	ery client and convert to Pandas							

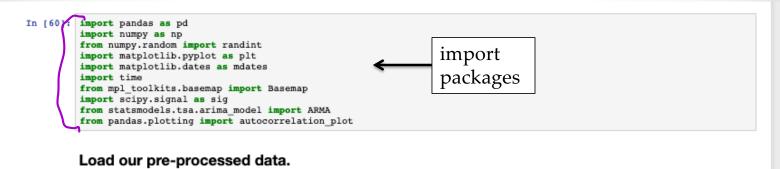
 More complex queries may include dataframe joins, aggregations, or subsetting

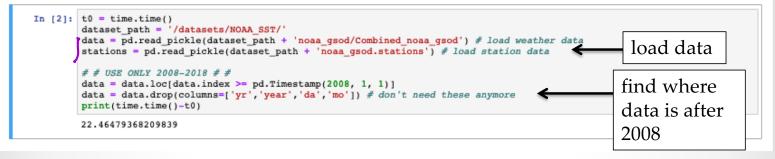
Tutorial Notebook

- Open "In-Class Tutorial"
- We will do:
 - 1. Load preprocessed data
 - 2. Define timeseries index
 - 3. Look at data
 - 4. Visualize station
 - 5. Detrend data
 - 6. Smooth data
 - 7. Try ARMA model

Tutorial Notebook

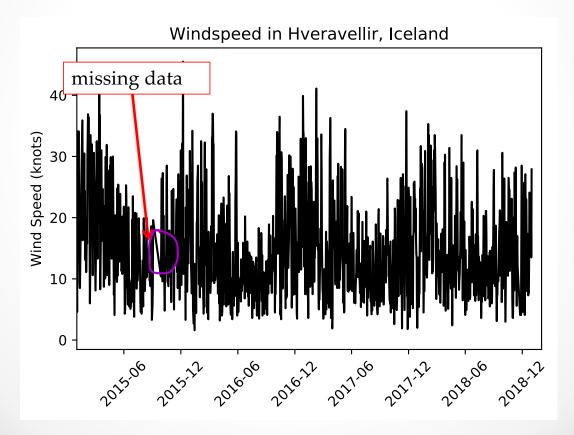
Load packages, (pre-processed) data with Pandas





Timeseries processing

- We may be missing data, but that's ok for now
- Replace with neighbor data, smooth, fill with mean



Where is my station located?

In [5]: my_station = stations.loc[stations['usaf'] == my_station_number]
my_station.head()

 usaf
 wban
 name
 country
 state
 call
 lat
 lon
 elev
 begin
 end

 18673
 041560
 99999
 HVERAVELLIR
 IC
 None
 64.867
 -19.567
 +0641.0
 20080115
 20190401

In [6]: fig = plt.figure(figsize=(15,7))

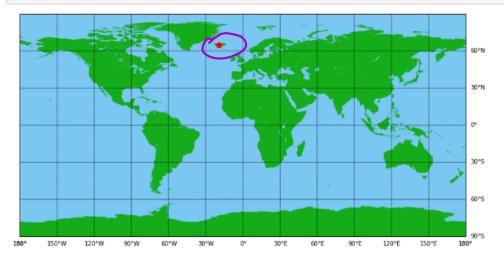
draw the oceans and countries and lines
m.drawmapboundary(fill_color='xkcd:lightblue')

m.fillcontinents(color='xkcd:green',lake_color='xkcd:lightblue')
m.drawmeridians(np.arange(0.,350.,30.),labels=[True,False,False,True])
m.drawparallels(np.arange(-90.,90,30.),labels=[False,True,True,False])

Basemap is handy but some problems if running on your laptop

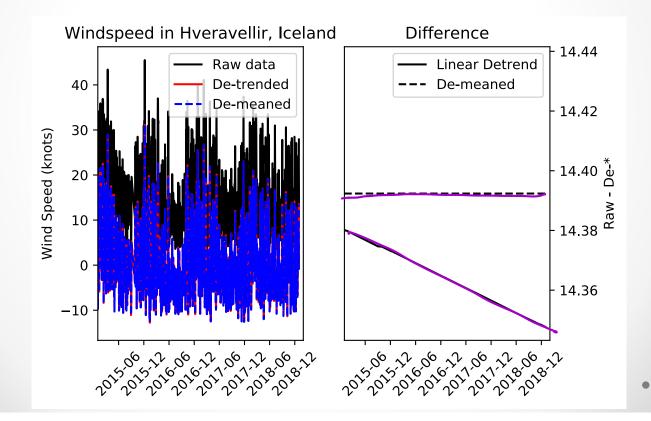
show my station

pl, = plt.plot(my_station['lon'],my_station['lat'],'rp', markersize=10)
plt.show()



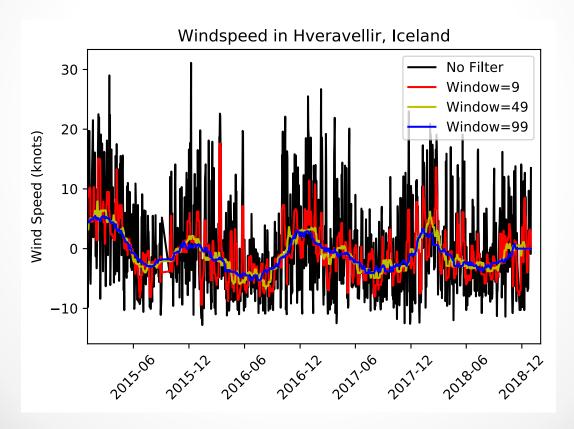
Timeseries processing

- Remove mean (slope=0) or linear (slope ≠ 0)? (linear)
- What can we learn from trend?

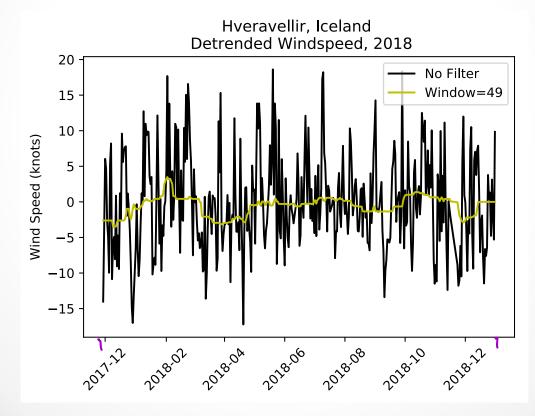


Timeseries processing

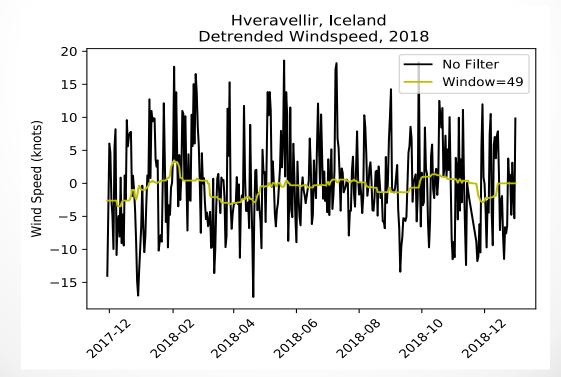
• Smoothing: median filter



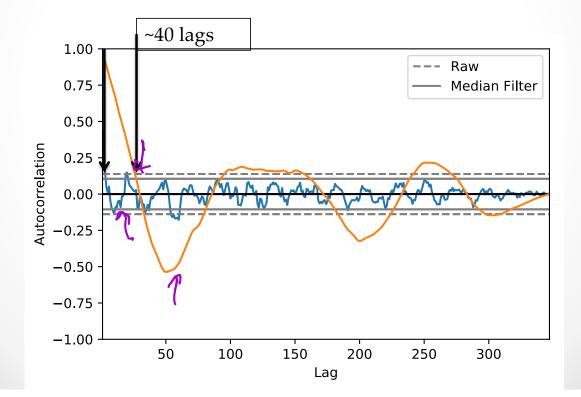
- Shortened timeseries Y2018 (final 10%)
- ARMA most effective predicting one step at a time



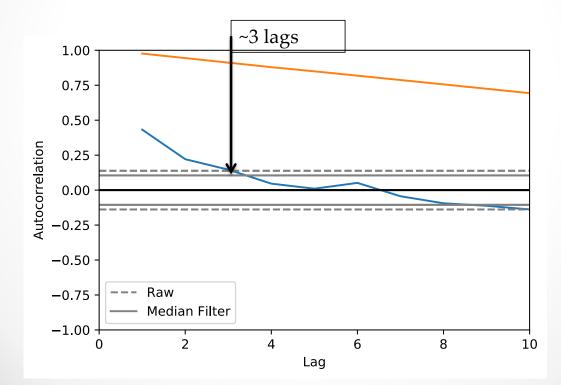
- Is ARMA a machine learning technique? (I think so..)
 - Filtering method (like Kalman filter)
 - o Data-driven
 - Maximum likelihood
 - Conclusion: statistics-based



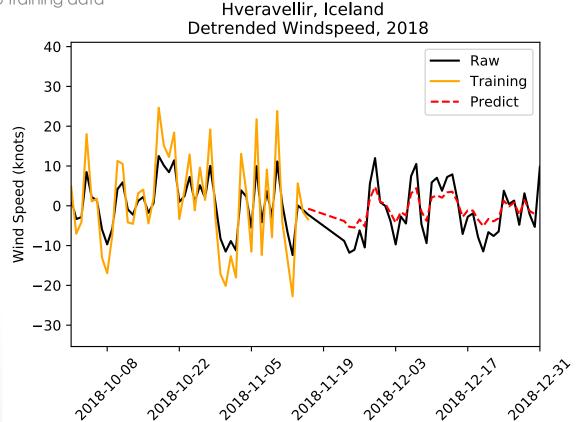
- Autocorrelation:
 - A statistical method to find temporal (or spatial) relations in data
 - When can reject the null hypothesis that the data is statistically similar?
 - E.g. How many time steps before the data is decorrelated



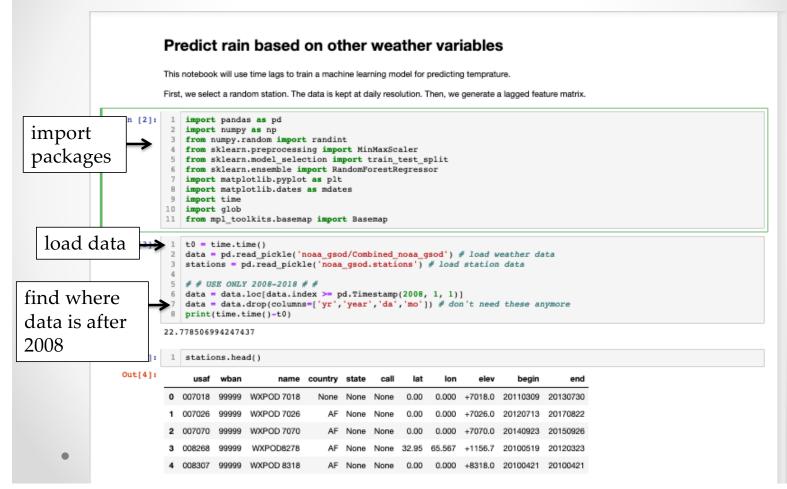
- Median filter increases decorrelation scale
 - By averaging neighbor samples
- Raw series is more random
- Use raw timeseries



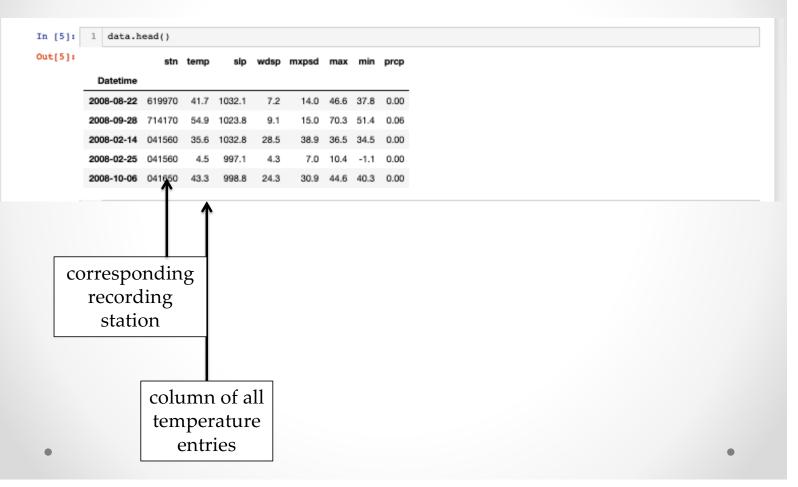
- ARMA algorithm:
 - 1. Train on all previous data
 - 2. Predict one time step
 - 3. Add next value to training data
 - 4. Repeat



How to load and preview data with Pandas



How to load and preview data with Pandas

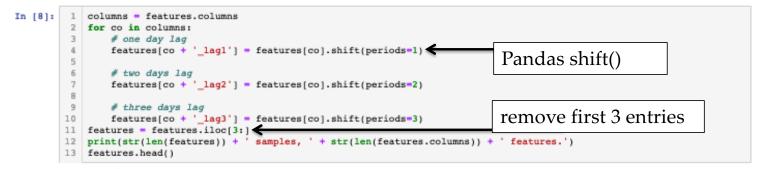


- Randomly select a station
- Check if the station has enough data
 - May reduce "3650" to lower number, i.e. 1000, but be aware you may have nans in data just look at it!



- Manually time-delay data
- Pandas "shift()"

Time-shift the data

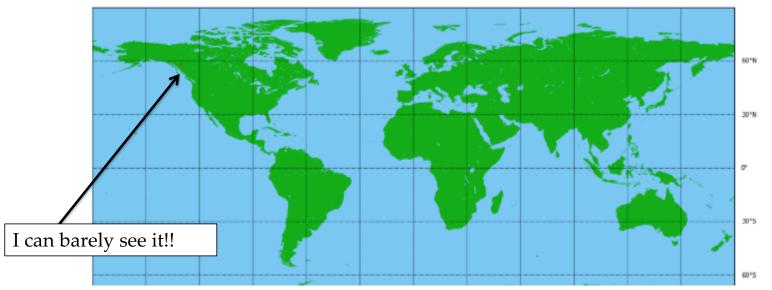


3926 samples, 20 features.

[8]:	temp	slp	wdsp	mxpsd	prcp	temp_lag1	temp_lag2	temp_lag3	slp_lag1	slp_lag2	slp_lag3	wdsp_lag1	wdsp_lag2	wdsp_l
Datetim	e													
2008-01 0	9.5	982.6	2.4	5.8	0.08	5.5	0.0	-1.7	991.0	998.5	1024.8	4.6	2.5	
2008-01 0	n n	978.9	2.2	4.9	0.03	9.5	5.5	0.0	982.6	991.0	998.5	2.4	4.6	
2008-01 0	11.4	987.0	2.8	5.8	0.12	6.6	9.5	5.5	978.9	982.6	991.0	2.2	2.4	
2008-01 0	-7.3	1005.2	3.7	7.0	0.00	11.4	6.6	9.5	987.0	978.9	982.6	2.8	2.2	
2008-01 0	-8.9	1005.8	5.3	9.9	0.00	-7.3	11.4	6.6	1005.2	987.0	978.9	3.7	2.8	

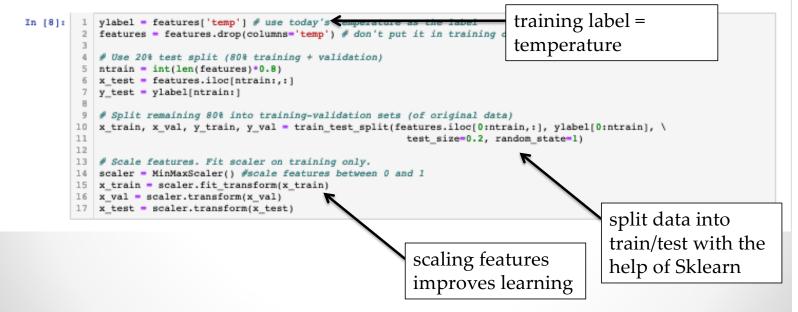
• (Map is supposed to show red "X" for station)





Snapshots from "timeseries_prediction_Temp.ipynb"

Create train/val/test

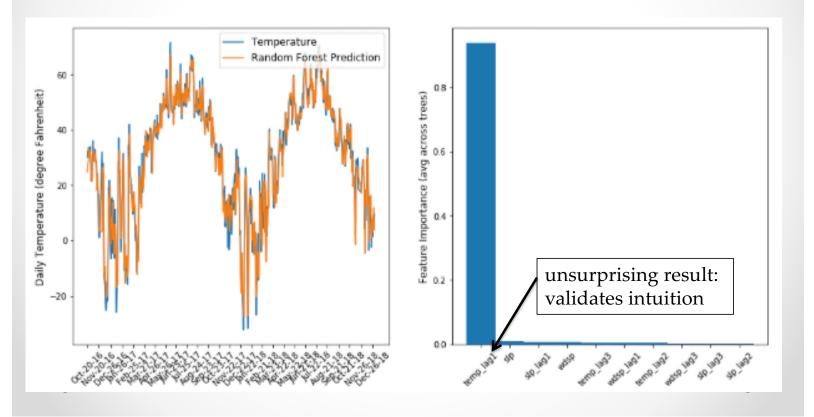


- Random forest model in a couple lines
- You may want to write a "plot.py" function

Predict with Random Forest



- Congratulations!
- We showed that tomorrow's temperature is usually similar to today's (at this Canada station)



Takeaway for your projects and beyond:

Have some dataset of interest but it has < ~1M images?

- 1. Find a very large dataset that has similar data, train a big ConvNet there
- 2. Transfer learn to your dataset

Deep learning frameworks provide a "Model Zoo" of pretrained models so you don't need to train your own

Caffe: <u>https://github.com/BVLC/caffe/wiki/Model-Zoo</u> TensorFlow: <u>https://github.com/tensorflow/models</u> PyTorch: <u>https://github.com/pytorch/vision</u>